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Behavioral description with message-passing

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Communicating Hardware Processes

- Behavioral language
 - CHP = Communicating hardware processes
 - Sequential Processes And A Based on Tony Hoare's CSP (Communicating Sequential Processes) language
- Simplified programming language
- Assignment-based language, but... No memory allocation ("new", "malloc", etc.) No memory references ("pointers", "references", etc.)
- Basic data types: Booleans and unsigned integers



bool x; int y; int < 8 > z;





Basic language constructs

- Simple statements
 - * skip statement that does nothing!
 - * x := E assignment statement
 - software programming language.

b := b & w |
$$\sim c$$

x := y*3
x := y{3..2} + 7
x := {p,q{
* Sequencing: $S_1; S_2$

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• Evaluate expression on the right-hand side, assign it to the variable on the left-hand side: just like a standard

+ 5	b+		w–
32}}	x :=	(a > 0 3	<pre>? b : myf(c,d))</pre>

ip;

https://avlsi.csl.yale.edu/act/doku.php?id=language:expressions





Arrays

• In hardware, an array results in an address-calculation mechanism

x[i] := x[i] + 1

- Array access is of two kinds
 - Standard array, where array index requires run-time information, or
 - Array index is a run-time constant

x[0] := x[0] + 1

• Only use standard arrays when absolutely necessary!







Example ACT CHP program



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int x[3]; // C++ style comments // implicit: 32 bits

Note: in CHP, semi-colon is used as a separator (no trailing semi-colon)





Conditional execution via *selection* **statements**

• Selections : generalized if-statements

- If some condition (guard) is true, execute corresponding statement
- If all guards are false, then wait
- * If multiple guards are true, error!
- To allow multiple true options, use non-deterministic selection

$$[| x > 10 -> y := 3]$$

$$[| x < 10 -> y := 4]$$

$$[| x > 8 -> y := 7]$$

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The "chp-txt" sublanguage: text version of CHP

• Selections : generalized if-statements

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$$[| x < 10 -> y := 4]$$

$$[| x > 8 -> y := 7]$$

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chp-txt equivalent

select { case x > 10: y := 3; case x < 10: y := 4

chp-txt equivalent

arb select { case x > 10: y := 3;case x < 10: y := 4;case x > 8: y := 7





Loops

• While loop

• Generalized deterministic loop

- If some condition (guard) is true, execute corresponding block and then go back to the beginning of the loop
- ✤ All guards false: exit
- More than one true guard: error

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chp-txt equivalent

chp-txt equivalent







More language constructs

Internal parallelism: S₁, S₂



- Common short-hand
 - Infinite loop

*[true -> STMTS]

Wait for some condition

[COND -> skip]



*[STMTS]

[COND]

chp-txt equivalent

forever { STMTS

chp-txt equivalent

wait-for (COND)



Communication with other processes

- Hardware modules exchange information via communication channels
- Channel
 - single-sender, single-receiver
 - * a matching send and receive behaves as a distributed assignment

X!e		Evaluate "e" and			
		senanono	αιραιροπιλ		
send(X,	e)	chp-txt		C	

If these two ports are connected, then this has the net effect of



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Receive value from input port Y and assign it to variable "x"

• Channels are **blocking**: a send waits for matching receive, and a receive waits for a matching send.





Overall hardware description

- A *parallel* collection of communicating hardware processes By default, no shared state
- Connections between processes via channels to exchange information (General shared variables possible; ignoring for this summer school!)
- For this summer school, syntax for connections, type declarations, etc. in the **ACT** language There are other examples of CSP-like languages (e.g. Occam)







Example: one-place buffer

- One-place buffer, initially empty
 - Empty state
 - Only operation that is valid: read next input

L?x

- Final state: full
- ✤ Full state
 - Only operation that is valid: send value on output

R!x

- Final state: empty
- Empty state to empty state:

L?x; R!x

*[L?x; R!x]

- Buffer repeats this forever:
- forever { recv (L,x);
 send (R,x)
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```
defproc buffer(chan?(int) L; chan!(int) R)
int x;
         // local state
 chp {
   *[ L?x; R!x ]
 }
```







```
defproc adder(chan?(int) A,B; chan!(int) 0)
 int x,y; // local state
chp {
   *[ A?x, B?y;
      0!(x+y)
```

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Synchronization operations are part of message-passing



- Communication actions synchronize different parallel processes
 - system are doing.

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* Knowing where one process is in its local program can give you information about what other processes in the



Non-determinism induced by the environment

- Problem: two input ports **A** and **B** and one output **Z**
 - Receive the "next input" from either A or B
 - Send this value on the output Z
- We need some new syntax!

Probe: "is there a communication pending on this port?"

• Use with care, and only when absolutely necessary

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