

# EENG 426/CPSC 459/ENAS 876 Silicon Compilation

## Synchronization

Computer Systems Lab  
<http://csl.yale.edu/~rajit>

Fall 2018

Yale

AVLSI

Manohar

EENG 426: Silicon Compilation

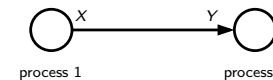
Fall 2018

1 / 10

## Communication

### Basic paradigm:

- Processes send and receive messages on communication ports.
- Connected ports form a communication channel.
- Messages cannot be received before they are sent  
⇒ synchronization



$X!e$ : send  $e$  on port  $X$

$Y?v$ : receive into  $v$  from port  $Y$

Yale

AVLSI

Manohar

EENG 426: Silicon Compilation

Fall 2018

2 / 10

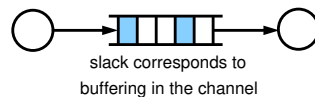
## Synchronization slack

To any command  $X$  we can attach a counter  $cX$ .

$cX \equiv \#$  of completed  $X$ -actions

We know that  $cS - cR \geq 0$ .

The maximum difference  $cS - cR$  is called the *slack* of the communication channel.



There are three possibilities:

- infinite slack
- positive, finite slack
- zero slack

Yale

AVLSI

Manohar

EENG 426: Silicon Compilation

Fall 2018

3 / 10

## Semantics of synchronization

We will mostly deal with slack zero channels. For these, we know that:

$$cS = cR$$

The completion of the  $N$ th send action coincides with the completion of the  $N$ th receive action.

What happens if a send action is reached, and the matching receive action has not yet been reached?

Yale

AVLSI

Manohar

EENG 426: Silicon Compilation

Fall 2018

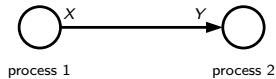
4 / 10

## Probes

If the send/receive is reached before the matching receive/send, then the operation blocks.

$\mathbf{q}X \equiv$  is there a pending  $X$ -action?

We use the *probe* to determine if the other end of the channel is ready.



$\bar{X}$  denotes the probe of  $X$

Rules:  $\bar{X} \Rightarrow \mathbf{q}Y$

$\mathbf{q}Y \Rightarrow \diamond \bar{X}$

Probes can only occur in guards.

Yale

AVLSI

Manohar

EENG 426: Silicon Compilation

Fall 2018

5 / 10

## Probes

Stability:

- If  $\bar{X}$  is true, it remains true until the next  $X$ -action. The true value of a probe is *stable*.
- If  $\bar{X}$  is false, it can change from false to true at any point. The false value of a probe is *unstable*.

Suspension:

If a communication action is probed, the process will never suspend at the communication action.

$\bar{X} \rightarrow \dots X?$

Yale

AVLSI

Manohar

EENG 426: Silicon Compilation

Fall 2018

6 / 10

## Communication

Matching sends and receives implement a form of *distributed assignment*.

$(X!e \parallel X?v) \equiv v := e$

**Convention:** use the same name to indicate that two ports form a channel.

We usually parameterize a process by its channels:

$P(A, B) \equiv *[ A?x; B!x ]$

Yale

AVLSI

Manohar

EENG 426: Silicon Compilation

Fall 2018

7 / 10

## Bullet

One more composition operator:

$S_1 \bullet S_2$

Both statements must be communication actions.

$\mathbf{c}S_1 = \mathbf{c}S_2$

Useful in development, because it tightly synchronizes different actions.

Operator precedence: bullet, comma, semicolon, parallel

Yale

AVLSI

Manohar

EENG 426: Silicon Compilation

Fall 2018

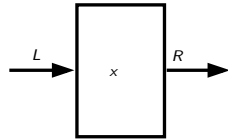
8 / 10

## One-place buffer

A one-place buffer:

```
*[ L?x; R!x ]
```

Can be thought of as slack on a channel, since slack corresponds to buffering.



How do we construct an  $N$ -place buffer?

## Merge

Two input channels, one output channel. The process merges the two input streams onto the output stream.

```
*[[  $\bar{X} \rightarrow X?a; Z!a$   
|  $\bar{Y} \rightarrow Y?a; Z!a$   
]]
```

Alternatively,

```
*[[  $\bar{X} \rightarrow X?a$   
|  $\bar{Y} \rightarrow Y?a$   
]; Z!a  
]
```